



LYNRED

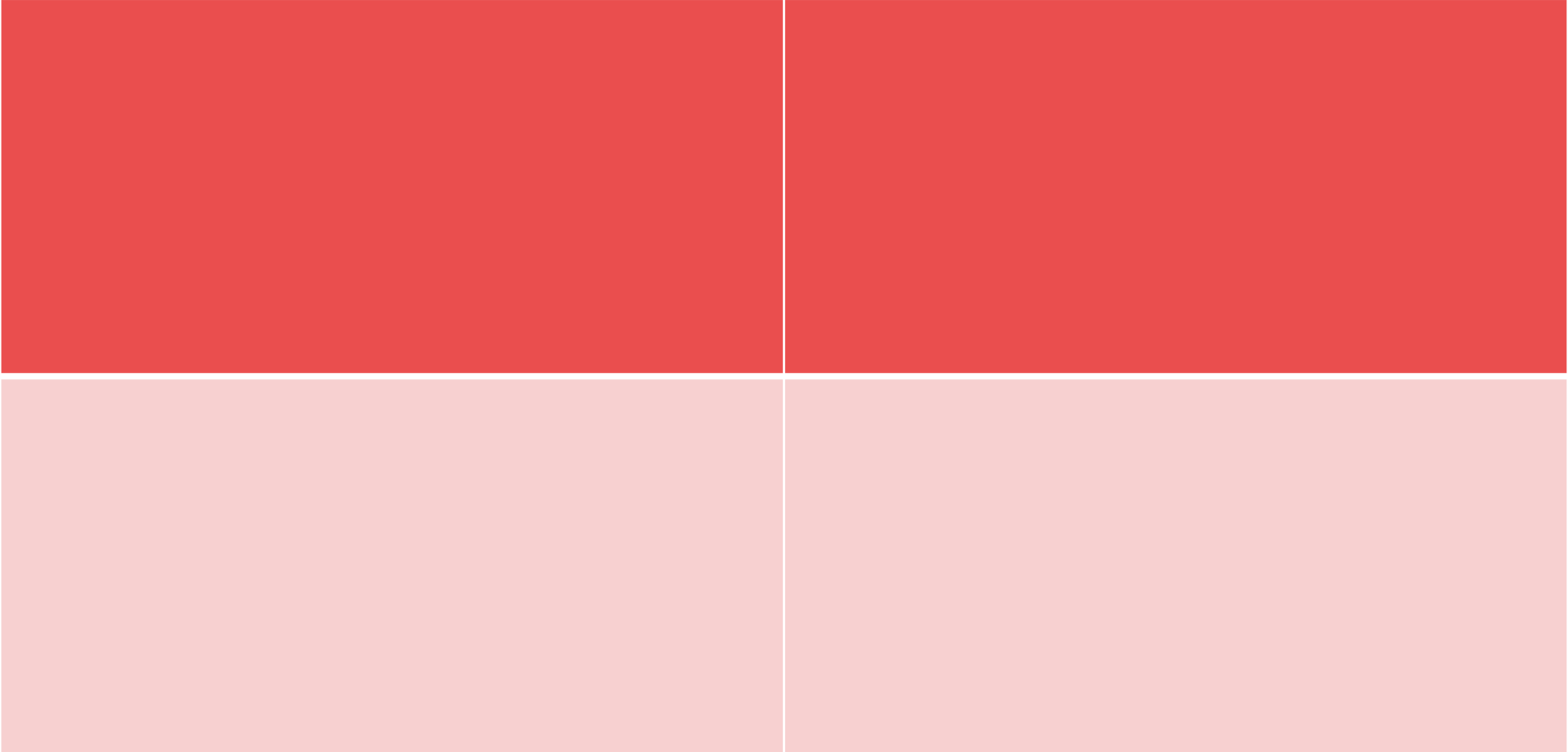
Latest electro-optical test means developments for SWIR band at LYNRED

L. Martineau¹, G. Bouchage¹, Q. Chable¹, R. Grille¹

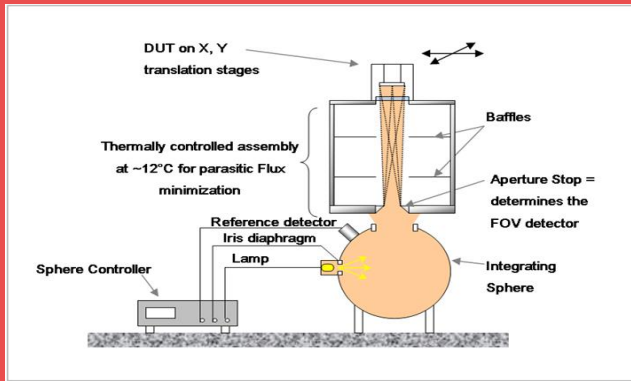
(1) LYNRED, Actipole - CS 10021, 364 route de Valence, 38113 Veurey-Voroize, France

**Infrared Detection for Space Applications Workshop • 7th- 9th June 2023, Toulouse
(France)**

Usual performance measurements

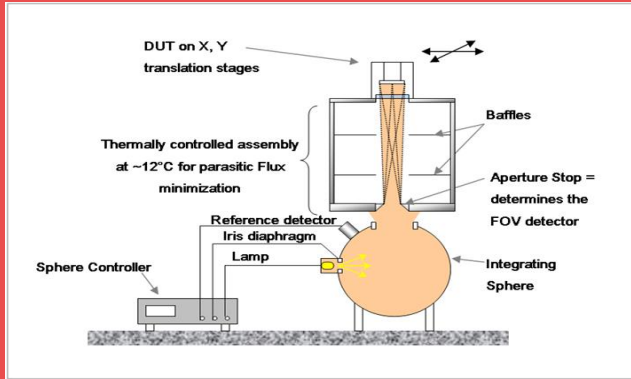


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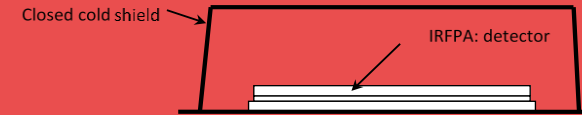


❑ Radiometric measurements

Usual performance measurements

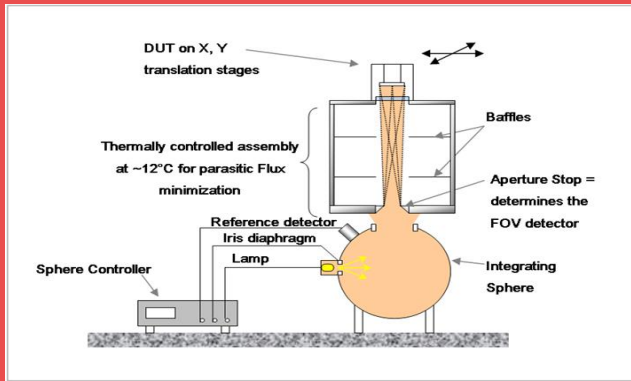


☐ Radiometric measurements



☐ Dark current measurements

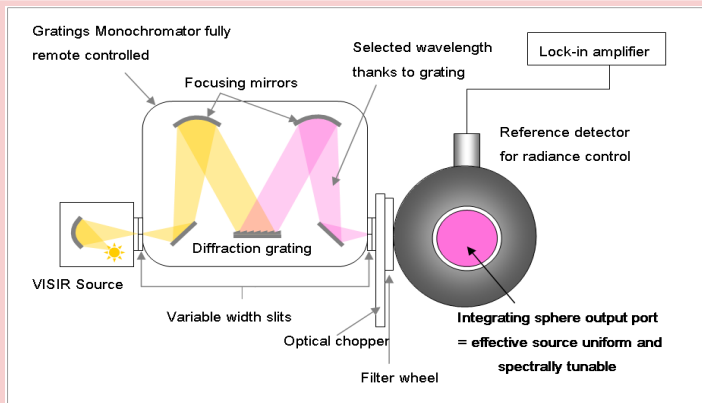
Usual performance measurements



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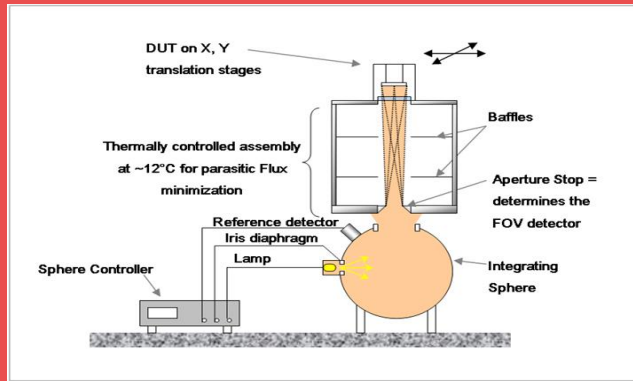


☐ Dark current measurements



☐ Spectral response measurements

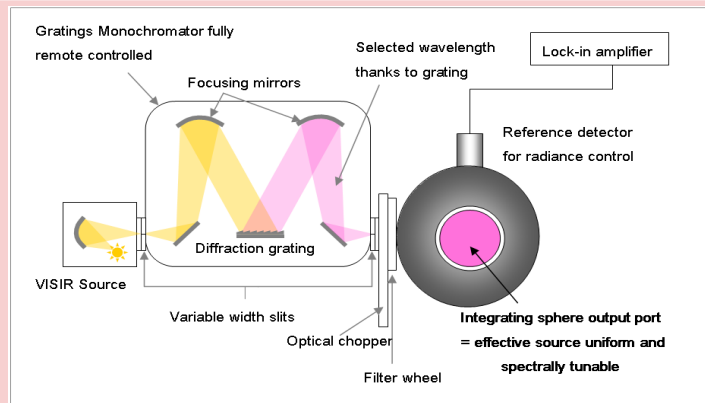
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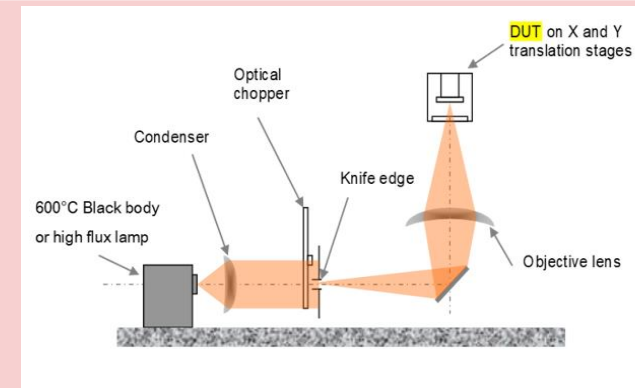
☐ Radiometric measurements



☐ Dark current measurements



☐ Spectral response measurements



☐ Geometrical measurements

Outline

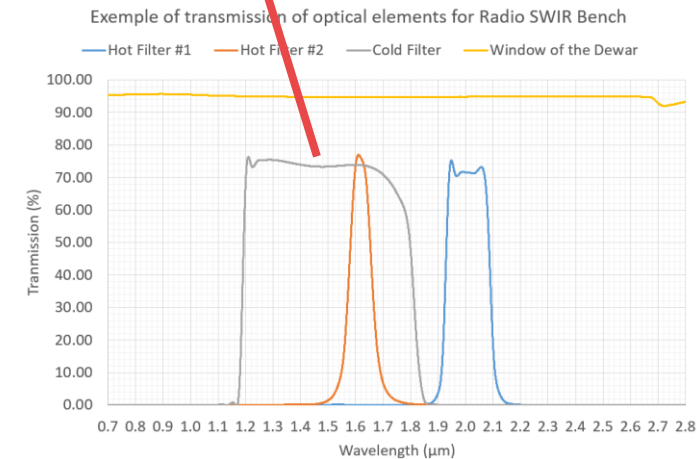
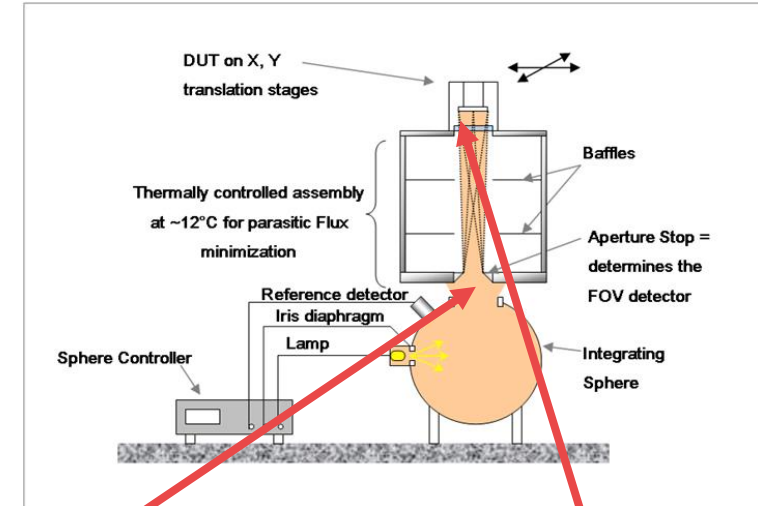
- ❑ Low background bench
- ❑ Spectral reconstruction
- ❑ Straylight analysis
- ❑ New bench concept

1

Low background
bench

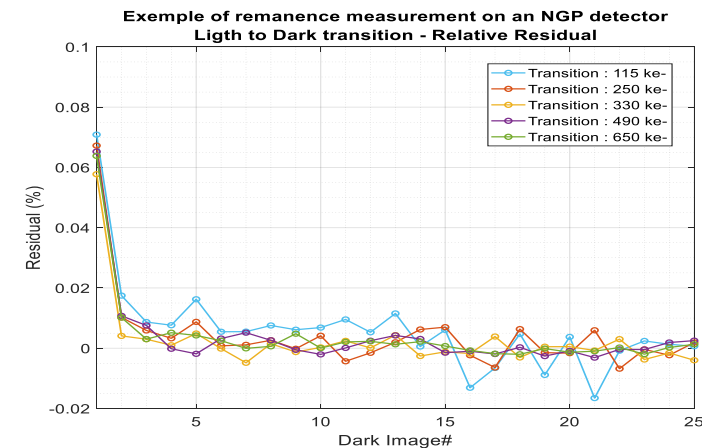
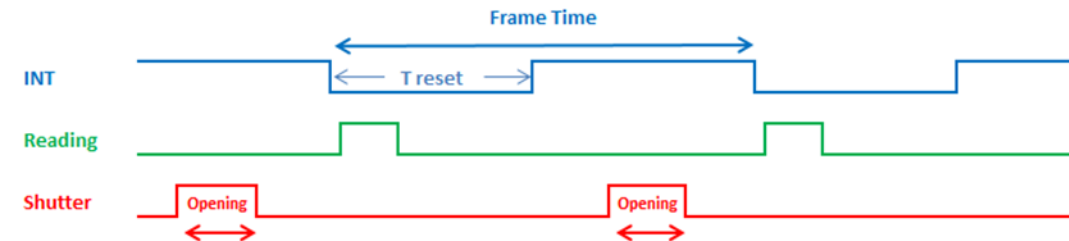
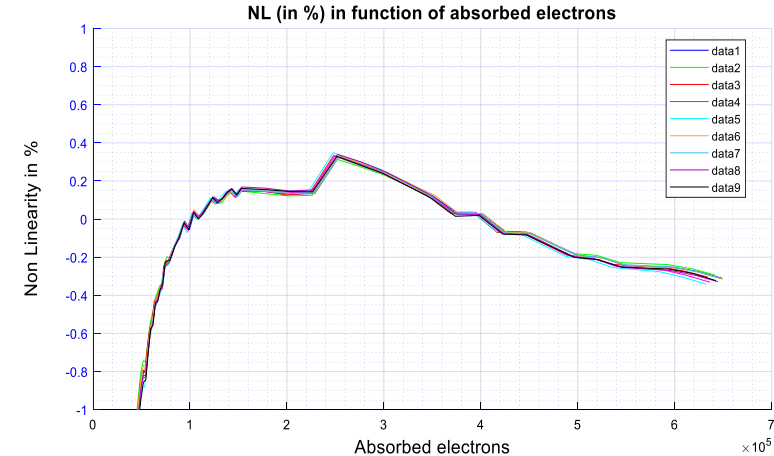
Radiometric measurements with low background flux

- ❑ Space program requires to reduce the background flux
- ❑ The solution described here is to insert a cold filter between the source and the detector
- ❑ For the lag measurement, a mechanical shutter is inserted between the source and detector to be measured with a typical switching time of 1ms.
- ❑ These solutions are compatible with existing SWIR benches and do not require large modifications



Results from this test configuration

- ❑ Background flux is reduced by ≈ 100 compared to the previous version
- ❑ Detector non-linearity is within $\pm 1\%$ on the useful flux range
- ❑ Light to dark (close) and dark to light (open) transitions were performed using the shutter on known detector.
- ❑ Measurements show lag residual close to measurement noises and are in agreement with expected lag of SWIR lag free detector.

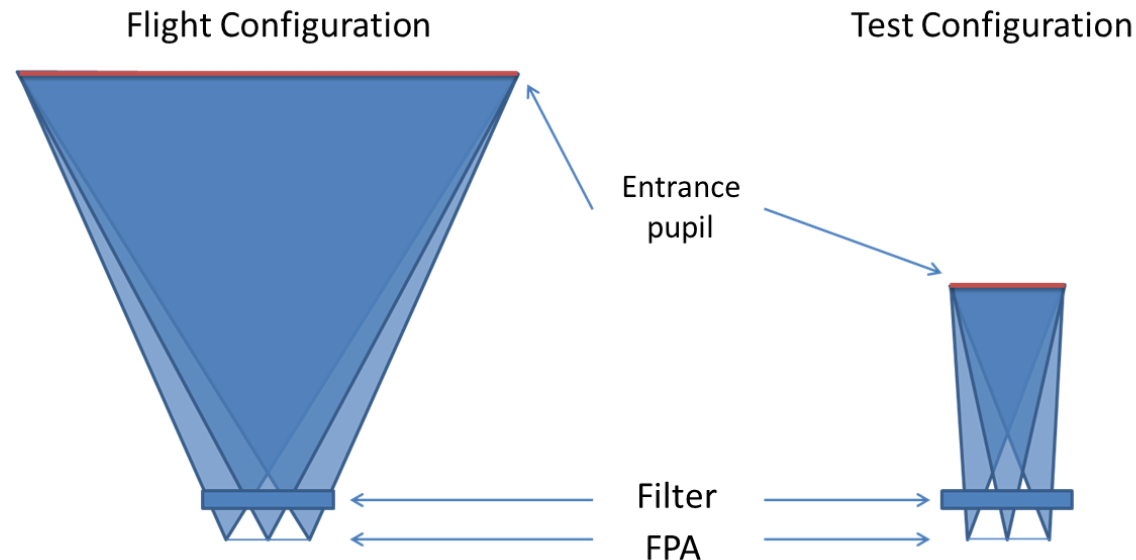


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Spectral reconstruction

Spectral response problem

- ❑ Spectral responses of the detector with built-in filters are different depending on optical configuration; it is the case between spectral responses obtained on characterization bench and the ones in final use (in flight)
- ❑ It is difficult to have a test bench adapted to instrument configuration, so one has to find a solution to be representative of the final use

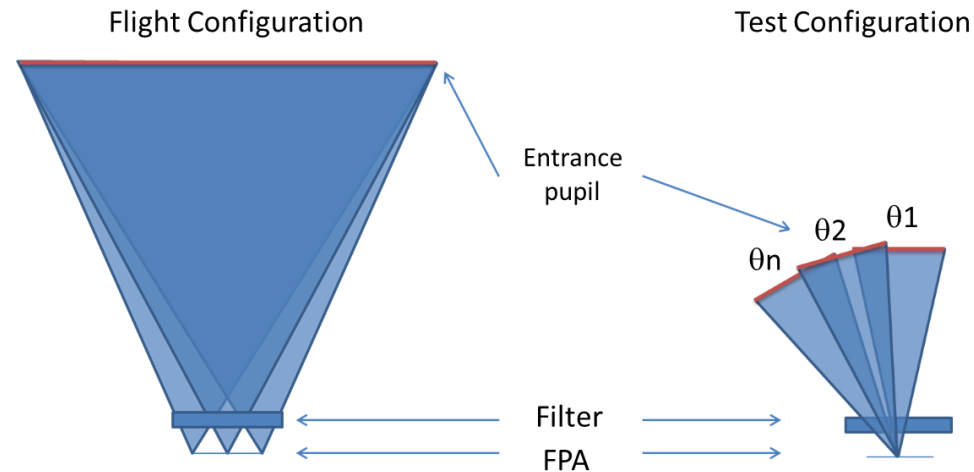


Spectral reconstruction

- ❑ As on the bench it is possible to perform spectral response at different angles, we can use a reconstruction method of $S(\lambda)$ to compensate for differences in illumination angles :

$$S(\lambda) = \sum_{\theta} S_{\theta}(\lambda) * w(\theta)$$

- ❑ Measurement configuration

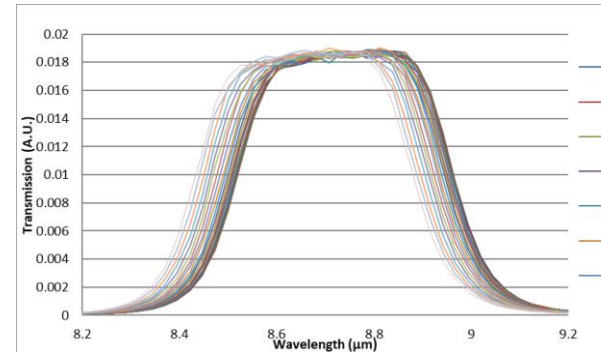
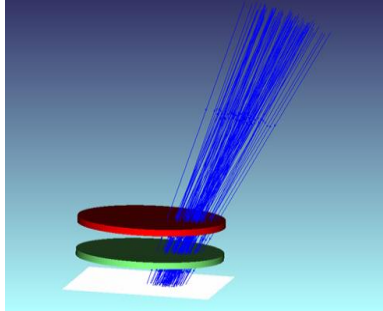


- ❑ The weight ($w(\theta)$) is calculated by fitting function (minimization) on angular distributions of each pupil :

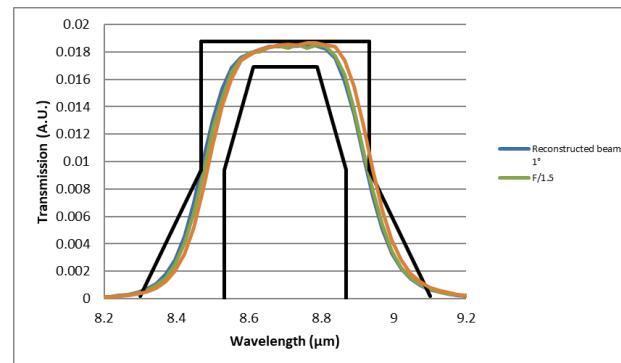
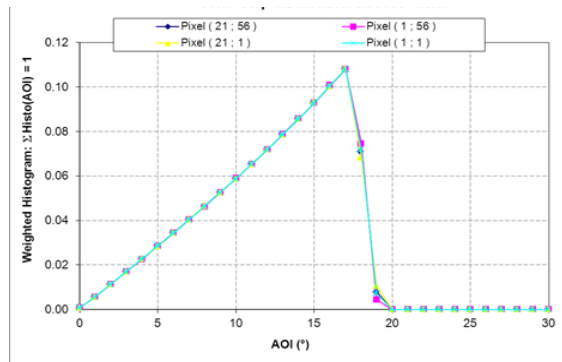
$$\min \left[AD_{flight} - \sum AD(\theta) * w(\theta) \right]$$

Method demonstration

- We use a Zemax model of the filter+window spectral responses to obtain spectral response at regularly spaced angles



- We then calculate the angular distribution of each pixel in flight to obtain the pixel response



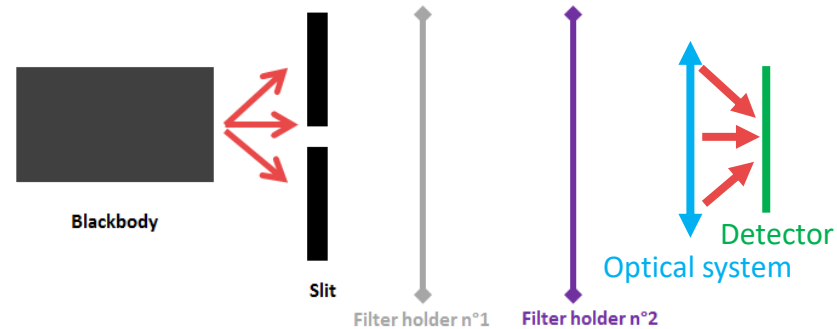
- This method has been applied on flight models and results are consistent with results at instrument level

3

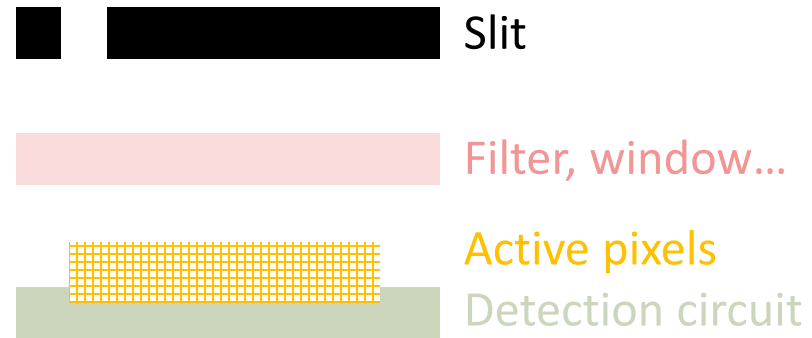
Straylight analysis

Straylight bench and measurement principle

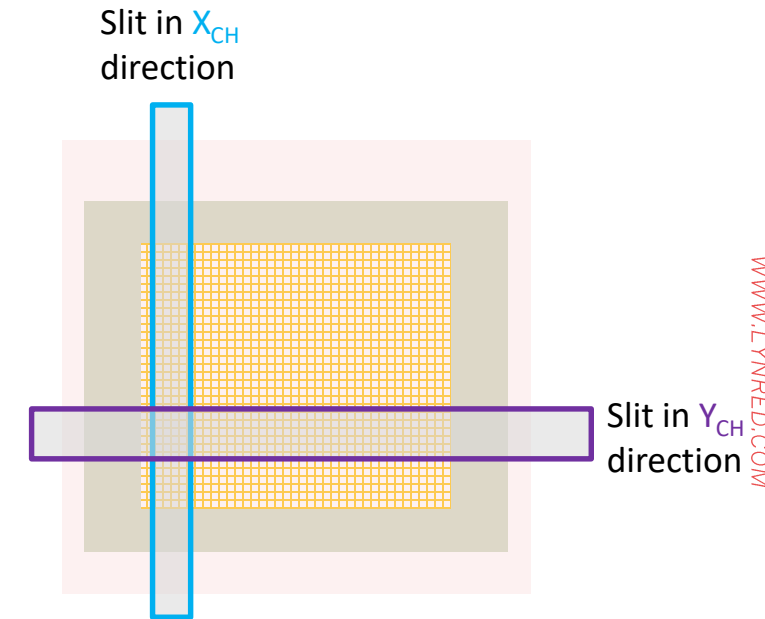
- ❑ Moving slit allows to illuminate part of the detector to verify straylight level



Bench geometry



Detector Package side view



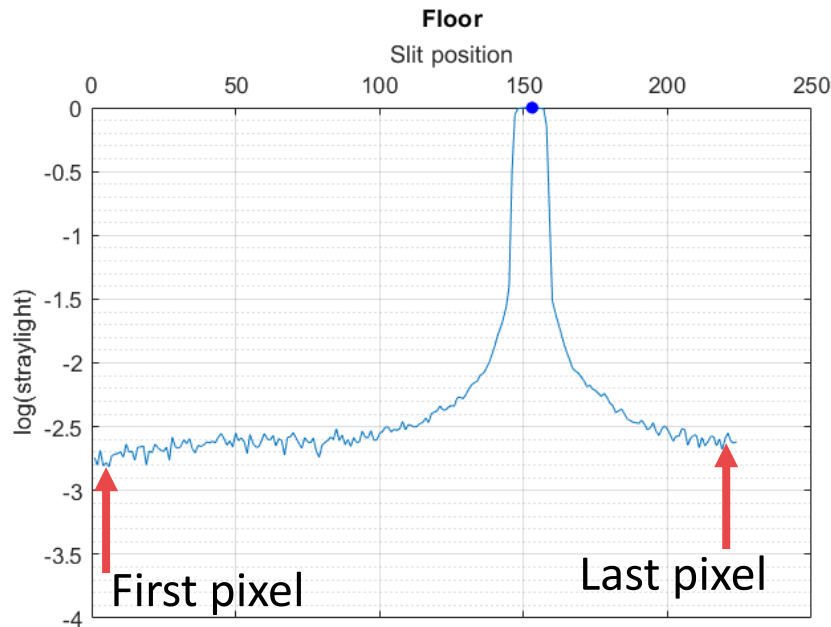
Detector Package top view

Straylight results

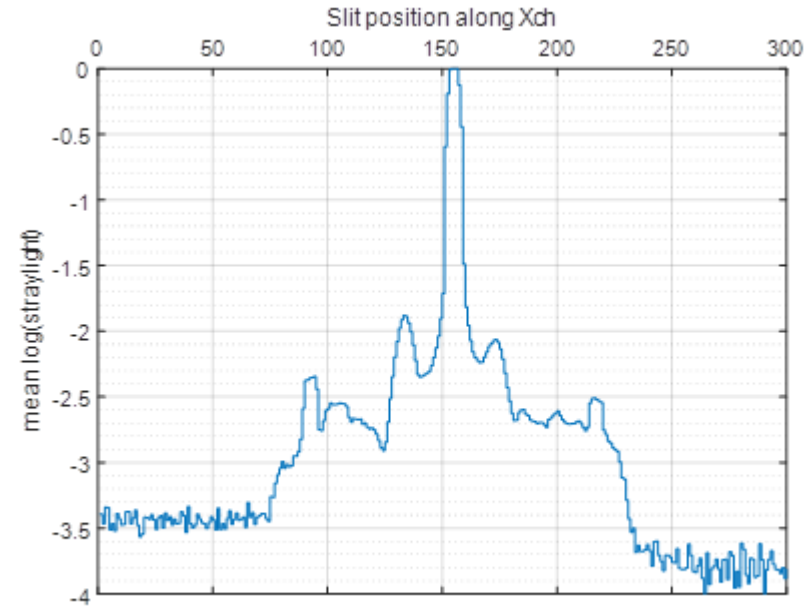
□ Y_{CH} : Floor level for all pixels not illuminated = no straylight

□ X_{CH} : Signal observed at other locations than active area = straylight

□ Peaks were studied and associated root cause identified
→ Correction and validation of detector package



Y_{CH} straylight at slit location 153
for all pixels of a column

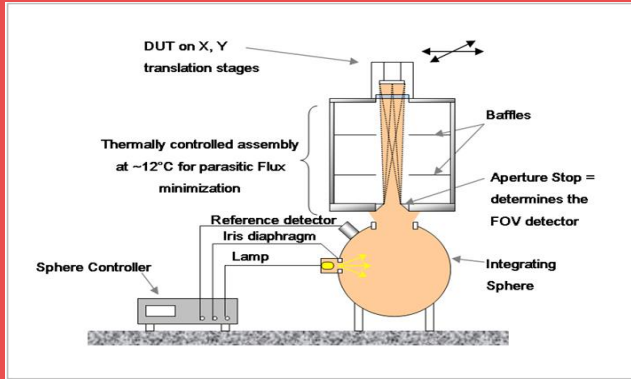


X_{CH} straylight at slit location from 0
to 300 (active area = 153).
Mean value of all pixels of a column

4

New bench concept

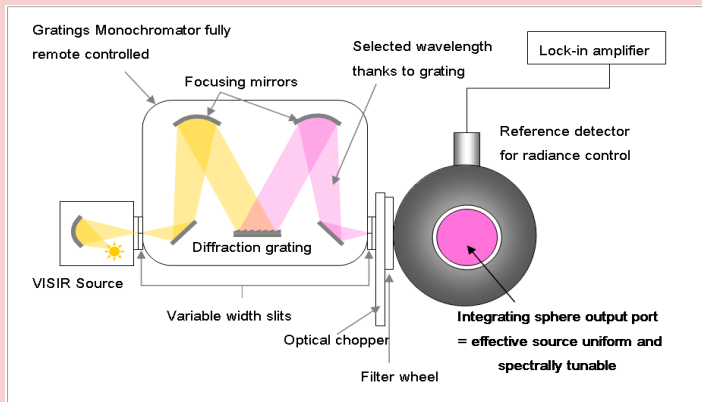
Ideal bench



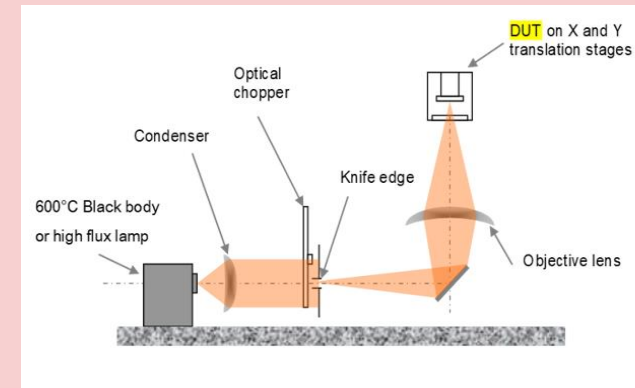
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☐ Dark current measurements

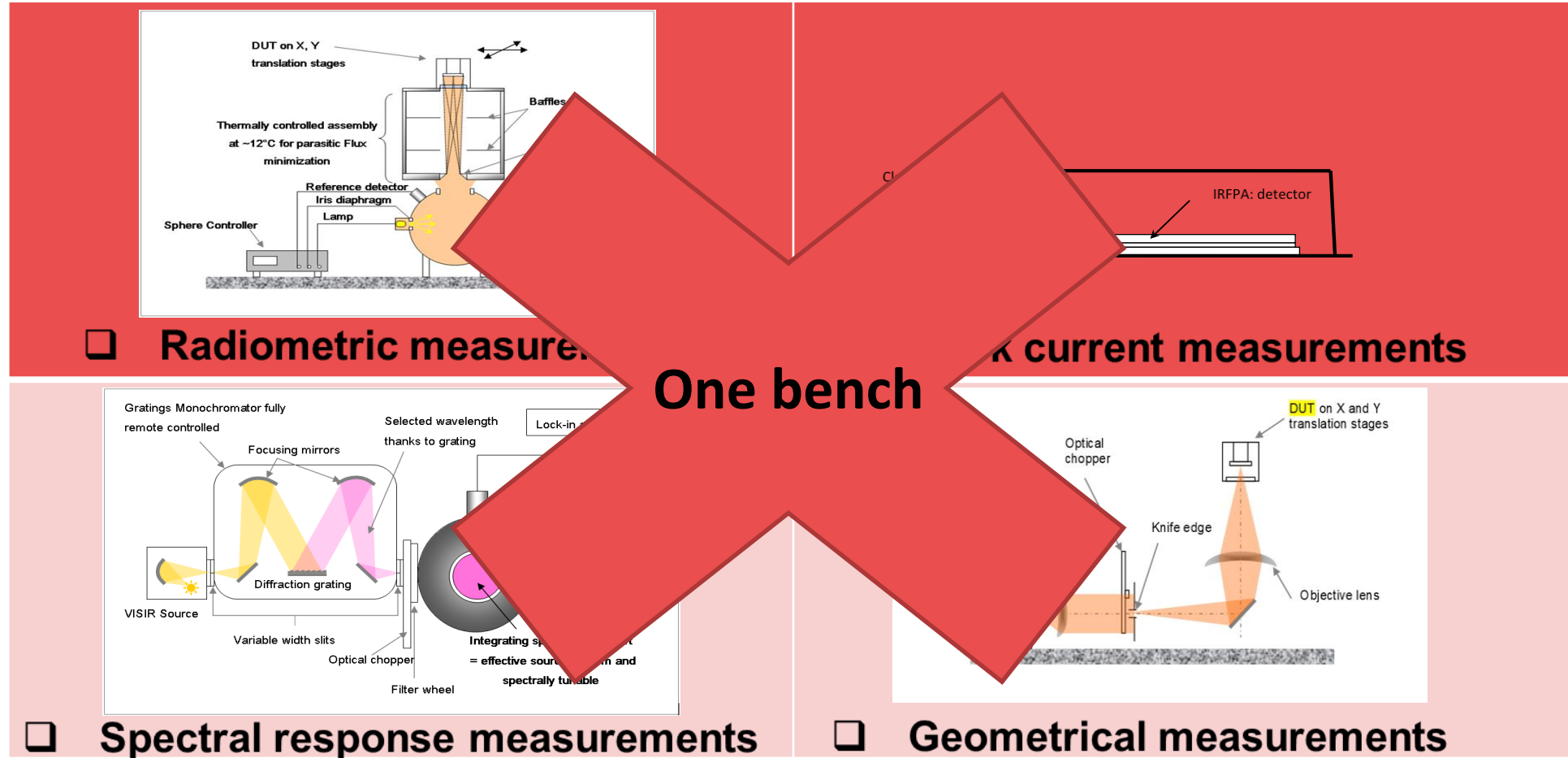


☐ Spectral response measurements



☐ Geometrical measurements

Ideal bench



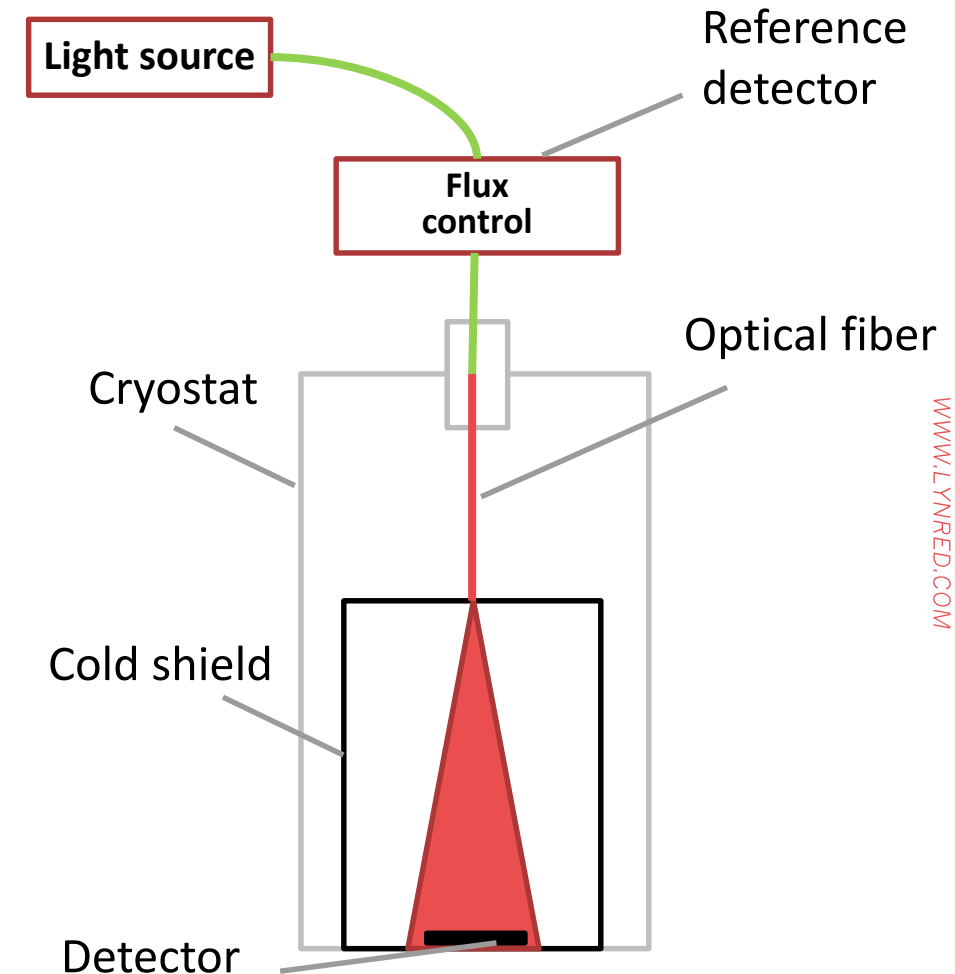
New bench concept

❑ Fiber background limited solution

- Stable light sources (centered on specified SWIR bands)
- Flux control module
- Fibered cold shield
- Built-in reference detector

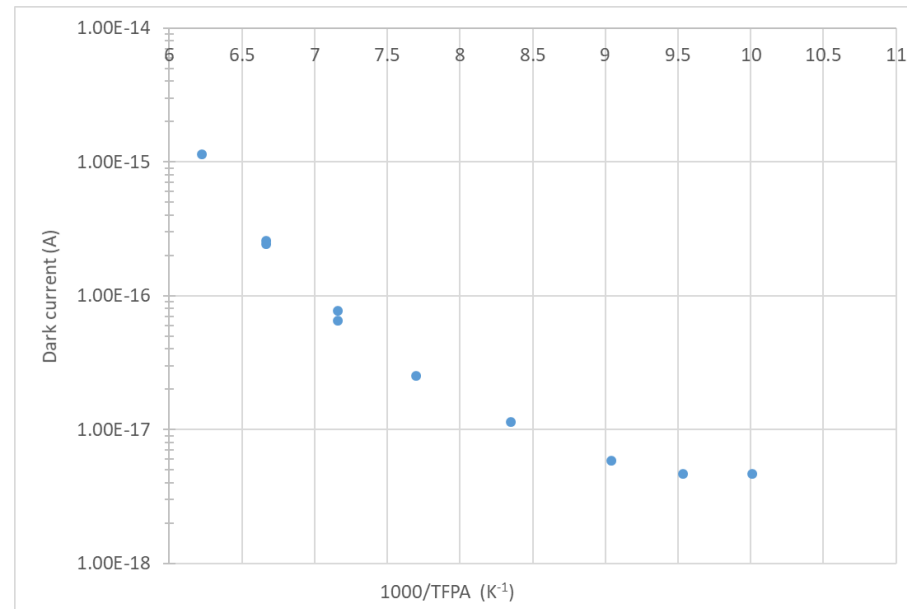
❑ Advantages

- Faster measurements (no configuration change)
- Low cost (built with cots parts)
- Compatible with our standard cryostats
- Reliable (no moving part)
- Accurate (no background)



Bench background validation

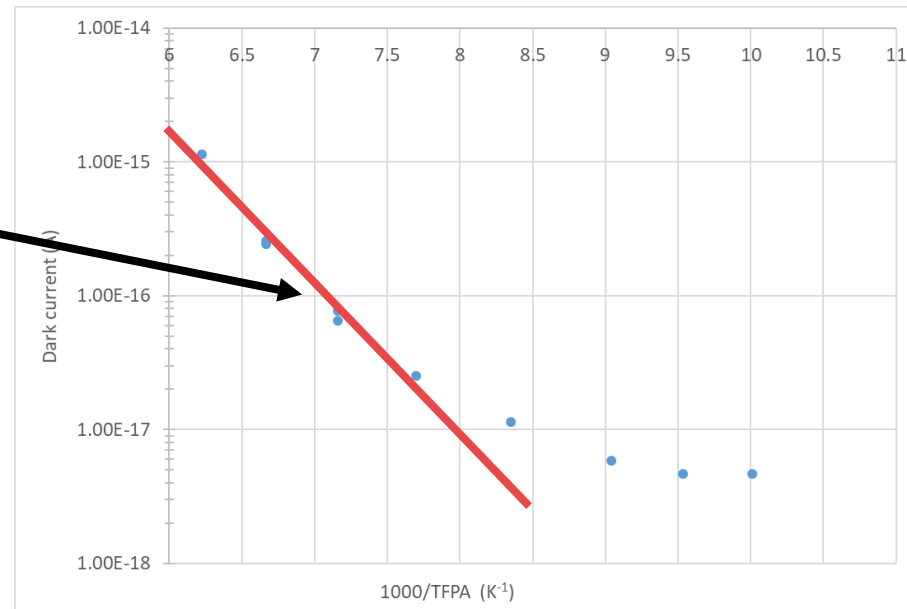
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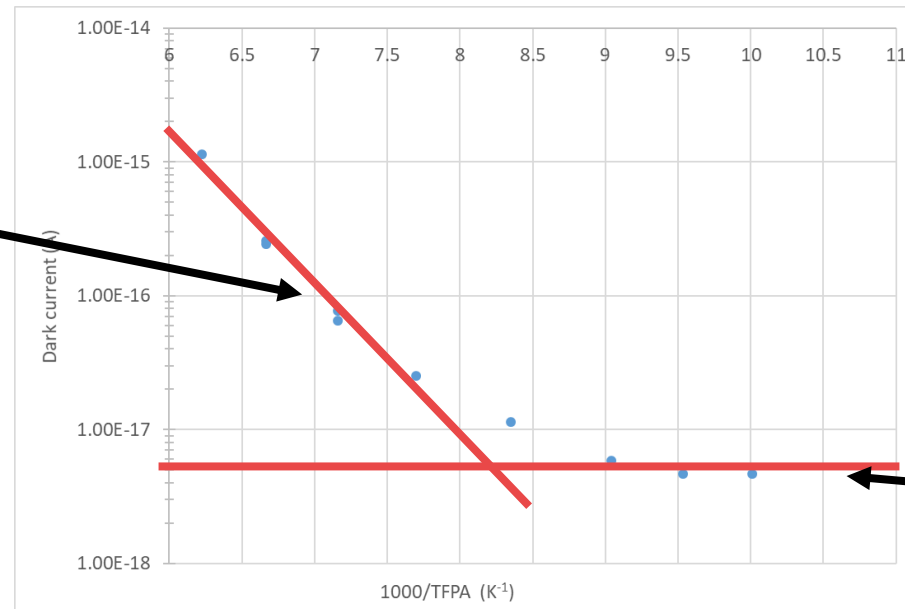
Dark current



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Dark current

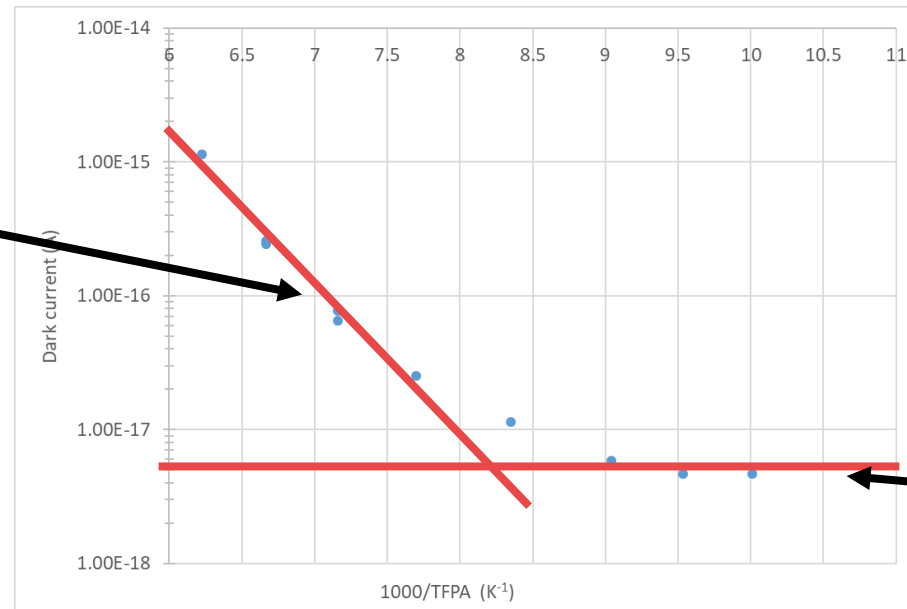


Background current

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Dark current

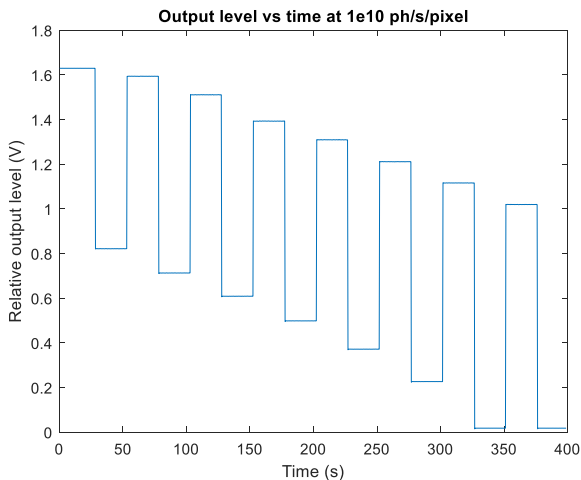


Background current

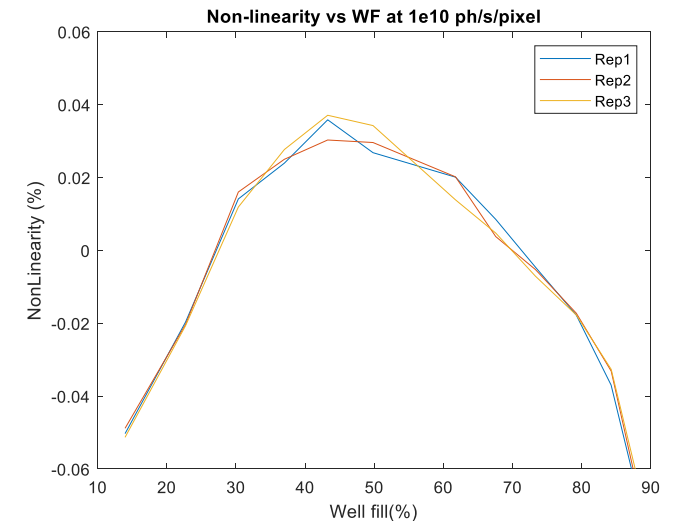
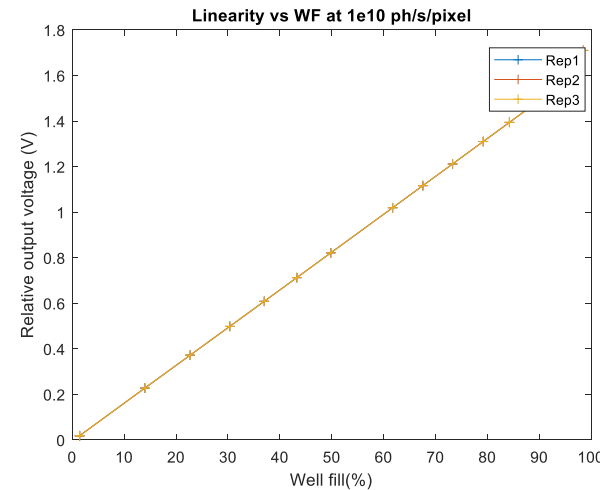
- ❑ Background current around $30\text{e-}/\text{s}$, so $\approx 100\text{x}$ gain compared to cold filter configuration
- ❑ Accurate dark current measurements down to $300\text{e-}/\text{s}$
- ❑ Flux measurements between 100 to 10^{10} ph/s/pixel for $15\mu\text{m}$ pitch

Linearity validation

- ❑ To evaluate linearity, we performed linearity measurements on a linear detector



$$\text{Non-linearity} = \frac{V_{\text{measured}} - V_{\text{fit}}}{\Delta V_{\text{max}}}$$

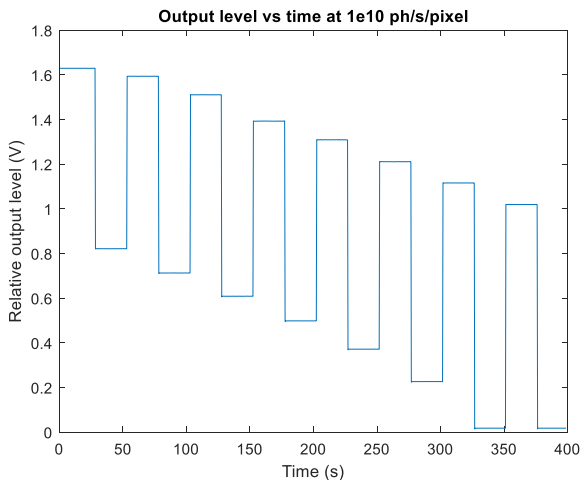


- ❑ Good reproducibility (between 0.001% to 0.01%)
- ❑ Good accuracy (in accordance with simulation)
- ❑ Fast measurement time: frame limited time (no delay between flux change)

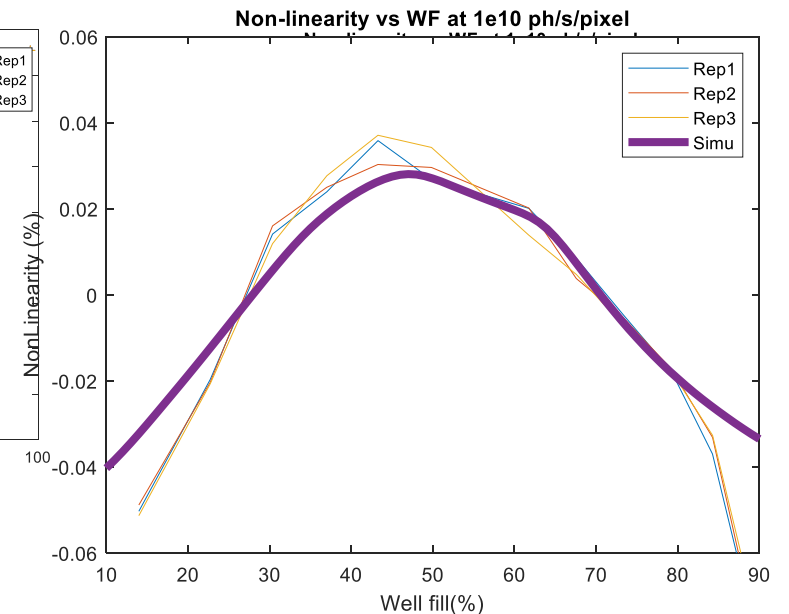
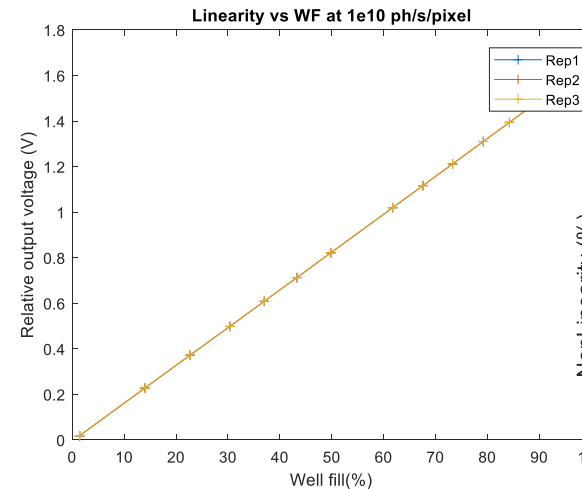
For 16 irradiances averaged over 70 frames of 350ms, linearity measurement time is approximately 400s

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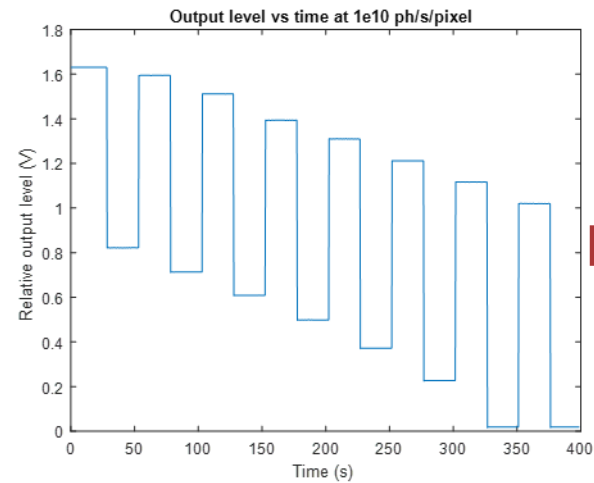


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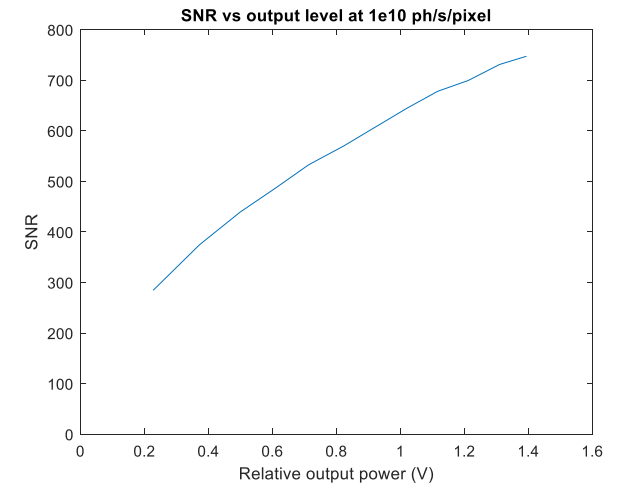
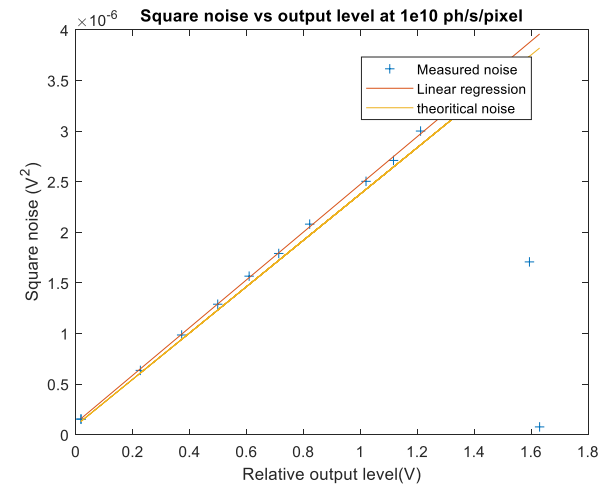
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SNR validation

- ❑ To evaluate SNR , we measured noise and compared it to the theoretical noise of the detector



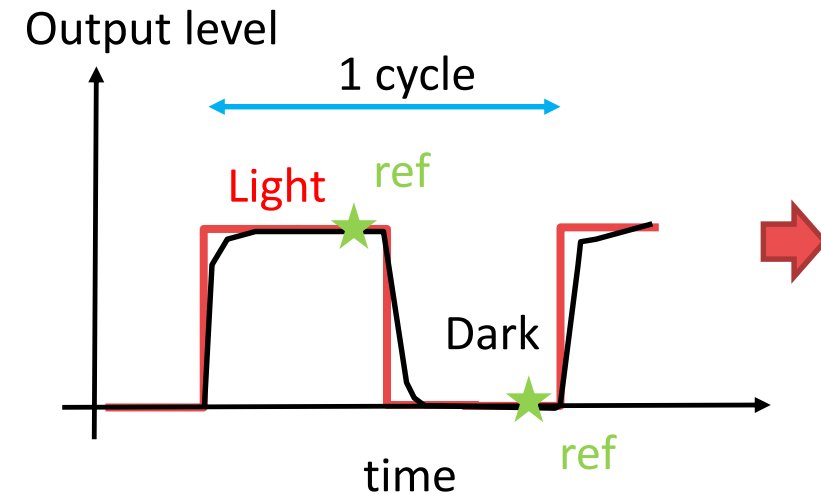
Standard deviation



- ❑ Performed at the same time as linearity measurements
- ❑ Measured noise closed to theoretical noise
- ❑ Relative accuracy close to few %

Lag validation

- ❑ To evaluate the lag, we perform a lag measurement on known detector with no lag.



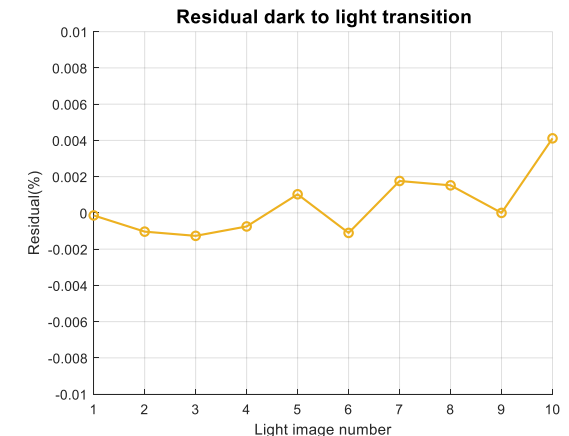
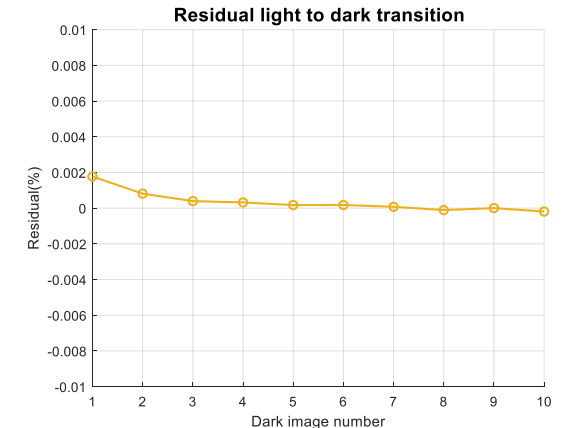
Light to dark transition

$$\text{Residual (trame } n) = \frac{\text{Dark}(n) - \text{Dark}(\text{ref})}{\text{Light}(\text{ref}) - \text{Dark}(\text{ref})} [\%]$$

Dark to light transition

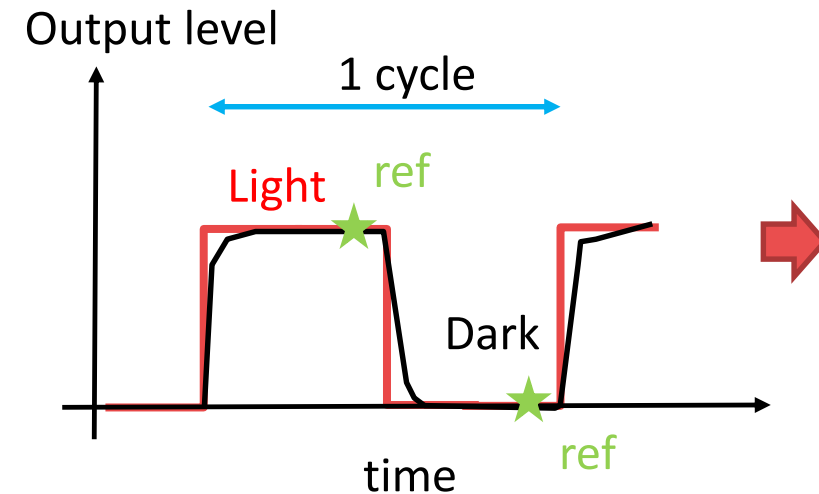
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- ❑ 10x gain on measurement limits
- ❑ Fast switching time (down to 1µs) of the flux module
- ❑ Possible to have any kind of irradiance transition
- ❑ Possible to choose excitation wavelength



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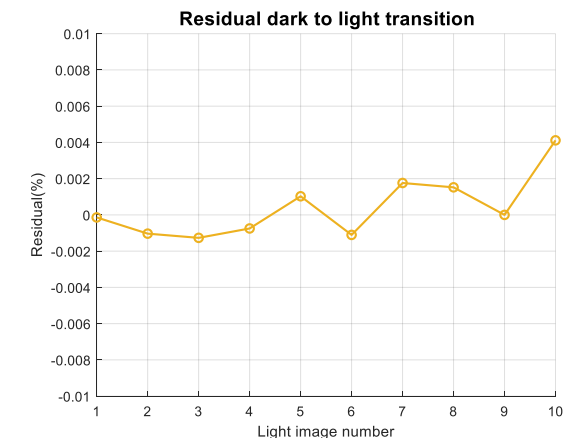
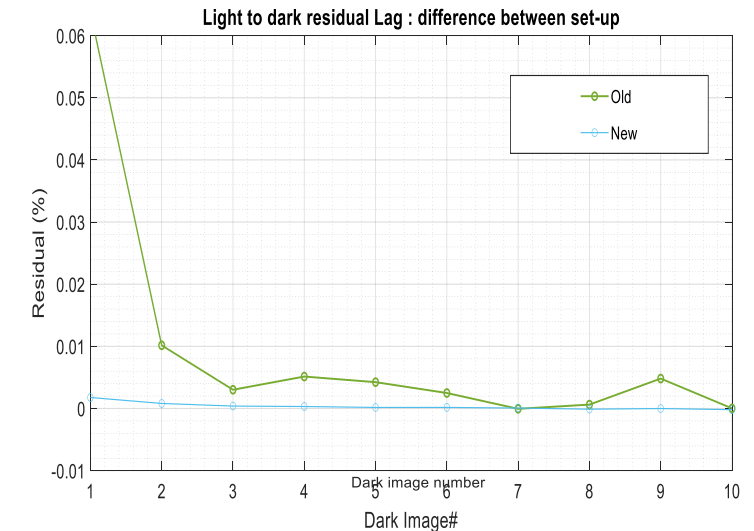
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5

Conclusion

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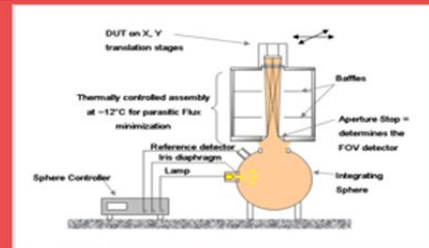
- ❑ **We saw that spatial test means have been developed over the years at Lynred to follow the detector developments and customer demands, and are clearly a key to program success.**

Conclusion

- ❑ **We saw that spatial test means have been developed over the years at Lynred to follow the detector developments and customer demands, and are clearly a key to program success.**
- ❑ **We demonstrated a new generation of test means allowing faster and more accurate measurements, and reducing drastically the detector test time.**

Conclusion

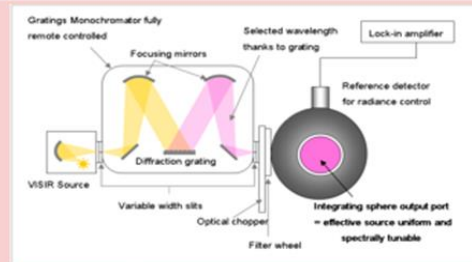
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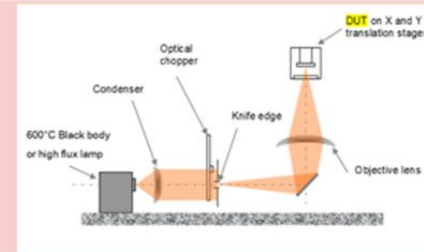
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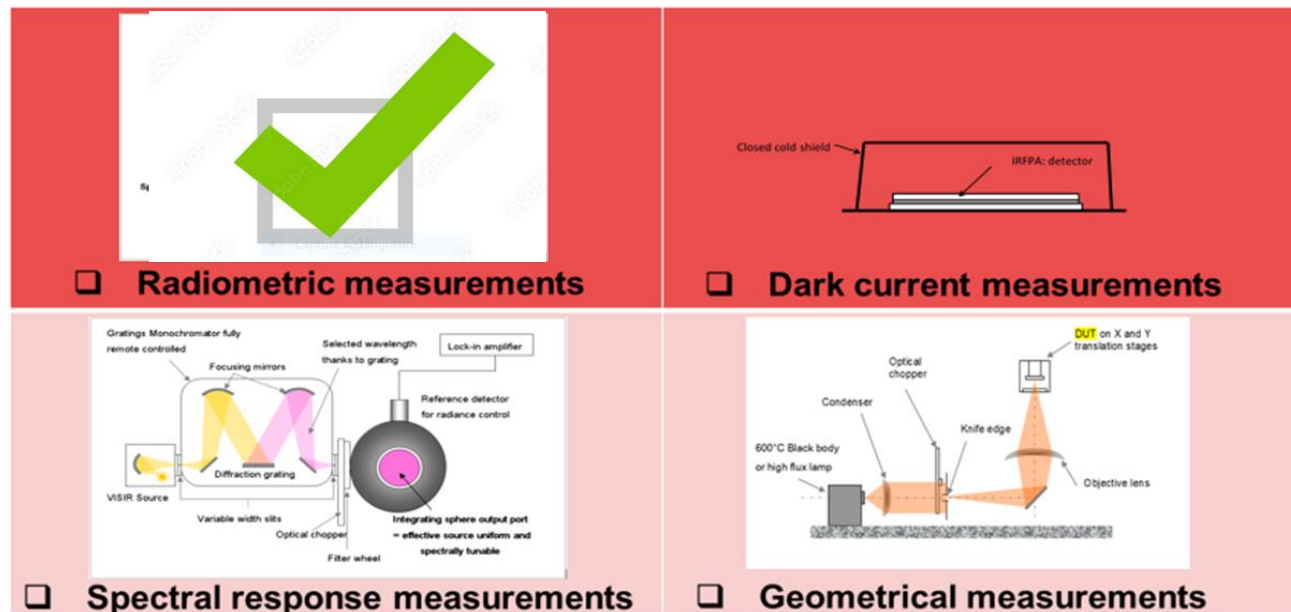
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❑ Geometrical measurements

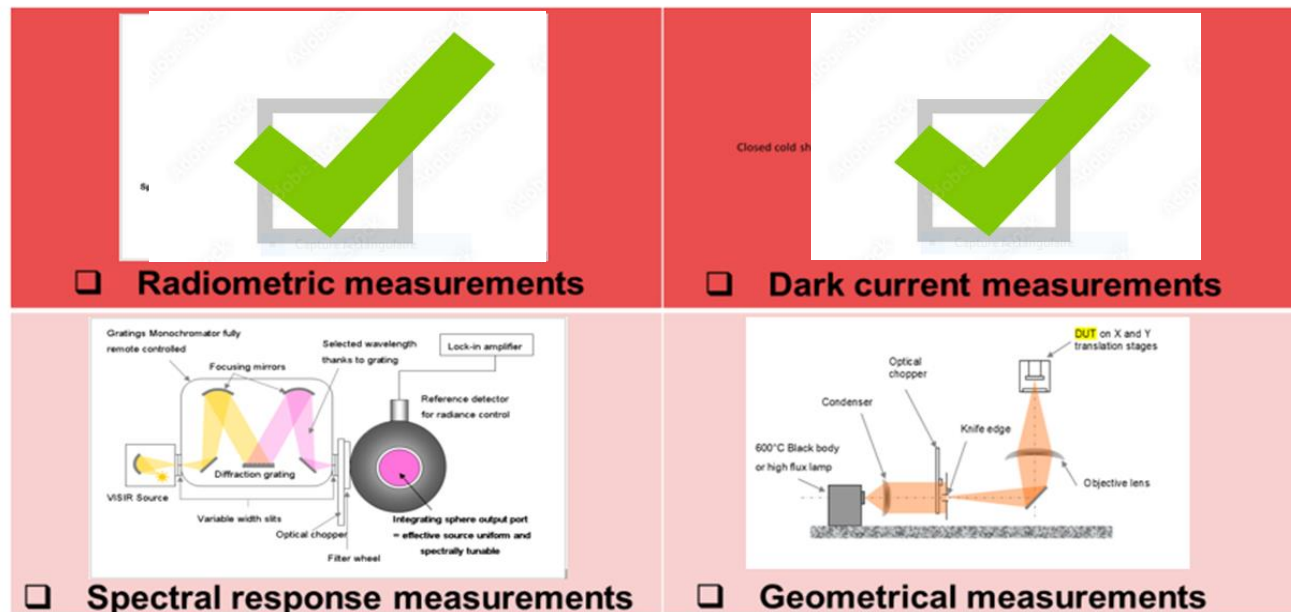
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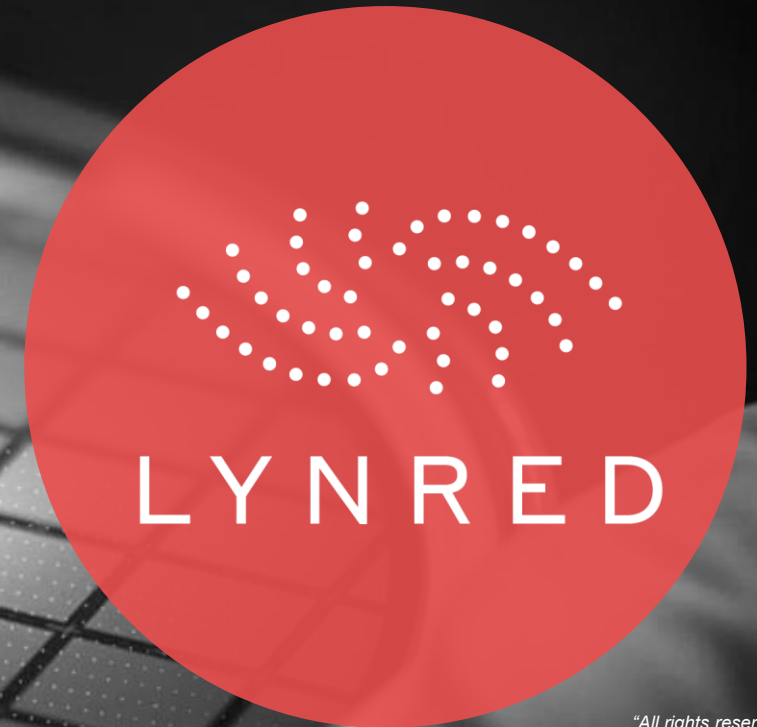
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THANK YOU
FOR YOUR ATTENTION



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